

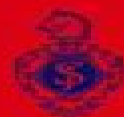


LECTURE NOTES IN CONTROL
AND INFORMATION SCIENCES

296

T. Matsuo
Y. Hasegawa

Realization Theory of Discrete-Time Dynamical Systems



Springer

Realization Theory Of Discretetime Dynamical Systems
Lecture Notes In Control And Information Sciences 296

Tsuyoshi Matsuo



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Realization Theory of Discrete-Time Dynamical Systems Tsuyoshi Matsuo, Yasumichi Hasegawa, 2003-10-08 This monograph extends Realization Theory to the discrete time domain It includes new results and constructs a new and very wide inclusion relation for various non linear dynamical systems After establishing some features of discrete time dynamical systems it presents results concerning systems which are proposed by the authors for the first time They introduce General Dynamical Systems Linear Representation Systems Affine Dynamical Systems Pseudo Linear Systems Almost Linear Systems and So called Linear Systems for discrete time and demonstrate the relationship between them and the other dynamical systems This book is intended for graduate students and researchers who study control theory

Realization Theory and Design of Digital Images Yasumichi Hasegawa, Tatsuo Suzuki, 2006-10-18 This monograph deals with the description and design of digital images Regarding digital images as special input output relations in our previous book with LNCIS series the description problem of digital images is transformed into the realization problem of digital images From the data in digital images mathematical models will be constructed Then new systems which describe faithfully any digital images provide new results and their extensions which design digital images As concerned with mathematical models for digital images this monograph introduces 2 Commutative Linear Representation Systems for two dimensional images and 3 Commutative Linear Representation Systems for three dimensional images This monograph is intended for researchers and graduate students who specialized in image processing and system theory

Switched and Impulsive Systems Zhengguo Li, Yengchai Soh, Changyun Wen, 2005-02-16 In this volume the important concept of switched and impulsive control is discussed with a wide field of applications in the analysis and control of complex systems This monograph provides the reader with a comprehensive coverage of switched and impulsive systems including new original work with various applications such as switched server systems scalable video coding systems chaotic based secure communication or quality of service on the internet Switched and Impulsive Systems can be used as a reference or a text for a course at graduate level

Identification of Nonlinear Systems Using Neural Networks and Polynomial Models Andrzej Janczak, 2004-11-18 This monograph systematically presents the existing identification methods of nonlinear systems using the block oriented approach It surveys various known approaches to the identification of Wiener and Hammerstein systems which are applicable to both neural network and polynomial models The book gives a comparative study of their gradient approximation accuracy computational complexity and convergence rates and furthermore presents some new and original methods concerning the model parameter adjusting with gradient based techniques Identification of Nonlinear Systems Using Neural Networks and Polynomial Models is useful for researchers engineers and graduate students in nonlinear systems and neural network theory

Hybrid Estimation of Complex Systems Michael W. Hofbauer, 2005-06-09 This monograph provides a tool set for hybrid estimation that can successfully monitor the behavior of complex artifacts with a large number of possible

operational and failure modes such as production plants automotive or aeronautic systems and autonomous robots For this purpose ideas from the fields of System Theory and Artificial Intelligence are taken and hybrid estimation is reformulated as a search problem This allows to focus the estimation onto highly probably operational modes without missing symptoms that might be hidden among the noise in the system Additionally a novel approach to continue hybrid estimation in the presence of unknown behavioral modes and to automate system analysis and synthesis tasks for on line operation are presented This leads to a flexible model based hybrid estimation scheme for complex artifacts that robustly copes with unforeseen situations

Control of Redundant Robot Manipulators Rajni V. Patel, F. Shadpey, 2005-05-04 This monograph provides a comprehensive and thorough treatment of the problem of controlling a redundant robot manipulator It presents the latest research from the field with a good balance between theory and practice All theoretical developments are verified both via simulation and experimental work on an actual prototype redundant robot manipulator This book is the first text aimed at graduate students and researchers working in the area of redundant manipulators giving a comprehensive coverage of control of redundant robot manipulators from the viewpoint of theory and experimentation

Explicit Stability Conditions for Continuous Systems Michael I. Gil, 2005-03-17 *Explicit Stability Conditions for Continuous Systems* deals with non autonomous linear and nonlinear continuous finite dimensional systems Explicit conditions for the asymptotic absolute input to state and orbital stabilities are discussed This monograph provides new tools for specialists in control system theory and stability theory of ordinary differential equations with a special emphasis on the Aizerman problem A systematic exposition of the approach to stability analysis based on estimates for matrix valued functions is suggested and various classes of systems are investigated from a unified viewpoint

Cooperative Control Vijay Kumar, Naomi Leonard, A. Stephen Morse, 2004-10-20 Are there universal principles of coordinated group motion and if so what might they be This carefully edited book presents how natural groupings such as fish schools bird flocks deer herds etc coordinate themselves and move so flawlessly often without an apparent leader or any form of centralized control It shows how the underlying principles of cooperative control may be used for groups of mobile autonomous agents to help enable a large group of autonomous robotic vehicles in the air on land or sea or underwater to collectively accomplish useful tasks such as distributed adaptive scientific data gathering search and rescue or reconnaissance

Sound Capture for Human / Machine Interfaces Wolfgang Herboldt, 2005-03-22 With a continuously increasing desire for natural and comfortable human machine interaction the acoustic interface of any terminal for multimedia or telecommunication services is challenged to allow seamless and hands free audio communication *Sound Capture for Human Machine Interfaces* introduces the practical aspects of microphone array signal processing and presents various combinations of beamforming and acoustic echo cancellation

American Book Publishing Record, 2004 Realization Theory of Continuous-time Dynamical Systems Tsuyoshi Matsuo, 1981 In this monograph I shall present a basis of realization theory of dynamical system Realization problem is to determine an intrinsic

mathematical model canonical dynamical system from the input output relations of a given causal black box i e to understand fully the internal behavior of the black box from the experimental data of it Moreover if possible we want to make the mathematical model real Realization theory was mainly developed in the field of discrete time linear systems as the algebraic system theory On the other hand it has been recognized that the highly developed automata theory has close relations with realization theory However there exist serious gaps between discrete time linear systems and automata for example the way of action of inputs on states are quite different In continuous time linear system the situation is worse There is no established way to think what is the set of input functions which act on states *Positive Systems* ,2006 Mathematical Reviews

,2005 **Subject Catalog** Library of Congress,1982 **Subject Catalog, 1982** Library of Congress,1982

Forthcoming Books Rose Arny,2003 *Subject Guide to Books in Print* ,1996 Control Problems of Discrete-Time Dynamical Systems Yasumichi Hasegawa,2015-01-20 This monograph deals with control problems of discrete time dynamical systems which include linear and nonlinear input output relations In its present second enlarged edition the control problems of linear and non linear dynamical systems will be solved as algebraically as possible Adaptive control problems are newly proposed and solved for dynamical systems which satisfy the time invariant condition The monograph provides new results and their extensions which can also be more applicable for nonlinear dynamical systems A new method which produces manipulated inputs is presented in the sense of state control and output control To present the effectiveness of the method many numerical examples of control problems are provided as well **Index of Mathematical Papers** ,1985

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