

Alexey S. Matveev
Andrey V. Savkin

Qualitative Theory of Hybrid Dynamical Systems

Qualitative Theory Of Hybrid Dynamical Systems Control Engineering Ser

**Keqin Gu, Vladimir L. Kharitonov, Jie
Chen**



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Qualitative Theory of Hybrid Dynamical Systems Alexey S. Matveev, Andrey V. Savkin, 2012-12-06 Hybrid dynamical systems both continuous and discrete dynamics and variables have attracted considerable interest recently This emerging area is found at the interface of control theory and computer engineering focusing on the analogue and digital aspects of systems and devices They are essential for advances in modern digital controller technology Qualitative Theory of Hybrid Dynamical Systems provides a thorough development and systematic presentation of the foundations and framework for hybrid dynamical systems The presentation offers an accessible but precise development of the mathematical models conditions for existence of limit cycles and criteria of their stability The book largely concentrates on the case of discretely controlled continuous time systems and their relevance for modeling aspects of flexible manufacturing systems and dynamically routed queuing networks Features and topics differential automata development and use of the concept cyclic linear differential automata CLDA switched single server flow networks coverage application to specific models of manufacturing systems and queuing networks select collection of open problems for the subject self contained presentation of topics with the necessary background This new book is an excellent resource for the study and analysis of hybrid dynamical systems used in systems and control engineering Researchers postgraduates and professionals in control engineering and computer engineering will find the book an up to date development of the relevant new concepts and tools

Hybrid Dynamical Systems Andrey V. Savkin, Robin J. Evans, 2002-07-10 This book is primarily a research monograph that presents in a unified manner some recent research on a class of hybrid dynamical systems HDS The book is intended both for researchers and advanced postgraduate students working in the areas of control engineering theoretical computer science or applied mathematics and with an interest in the emerging field of hybrid dynamical systems The book assumes competence in the basic mathematical techniques of modern control theory The material presented in this book derives from a period of fruitful research collaboration between the authors that began in 1994 and is still ongoing Some of the material contained herein has appeared as isolated results in journal papers and conference proceedings This work presents this material in an integrated and coherent manner and also presents many new results Much of the material arose from joint work with students and colleagues and the authors wish to acknowledge the major contributions made by Ian Petersen Efstratios Skafidas Valery Ugrinovskii David Cook Iven Mareels and Bill Moran There is currently no precise definition of a hybrid dynamical system however in broad terms it is a dynamical system that involves a mixture of discrete valued and continuous valued variables Since the early 1990s a bewildering array of results have appeared under the umbrella of HDS ranging from the analysis of elementary on off control systems to sophisticated mathematical logic based descriptions of large real time software systems

Stability and Control of Dynamical Systems with Applications Derong Liu, Panos J. Antsaklis, 2003-06-24 It is with great pleasure that I offer my reflections on Professor Anthony N Michel s retirement from the

University of Notre Dame I have known Tony since 1984 when he joined the University of Notre Dame's faculty as Chair of the Department of Electrical Engineering. Tony has had a long and outstanding career. As a researcher, he has made important contributions in several areas of systems theory and control theory, especially stability analysis of large-scale dynamical systems. The numerous awards he received from the professional societies, particularly the Institute of Electrical and Electronics Engineers (IEEE), are a testament to his accomplishments in research. He received the IEEE Control Systems Society's Best Transactions Paper Award 1978 and the IEEE Circuits and Systems Society's Guillemin-Cauer Prize Paper Award 1984 and Myril B. Reed Outstanding Paper Award 1993 among others. In addition, he was a Fulbright Scholar 1992 and received the Alexander von Humboldt Forschungspreis Alexander von Humboldt Research Award for Senior U.S. Scientists from the German government 1997. To date, he has written eight books and published over 150 archival journal papers. Tony is also an effective administrator who inspires high academic standards.

Stability and Convergence of Mechanical Systems with Unilateral Constraints Remco I. Leine, Nathan van de Wouw, 2007-12-29. Stability of motion is a central theme in the dynamics of mechanical systems. While the stability theory for systems with bilateral constraints is a well-established field, this monograph represents a systematic study of mechanical systems with unilateral constraints such as unilateral contact, impact, and friction. Such unilateral constraints give rise to non-smooth dynamical models for which stability theory is developed in this work. The book starts with the treatise of the mathematical background on non-smooth analysis, measure, and integration theory, and an introduction to the field of non-smooth dynamical systems. The unilateral constraints are modelled in the framework of set-valued force laws developed in the field of non-smooth mechanics. The embedding of these constitutive models in the dynamics of mechanical systems gives rise to dynamical models with impulsive phenomena. This book uses the mathematical framework of measure differential inclusions to formalise such models. The book proceeds with the presentation of stability results for measure differential inclusions. These stability results are then applied to nonlinear mechanical systems with unilateral constraints. The book closes with the study of the convergence property for a class of measure differential inclusions, a stability property for systems with time-varying inputs, which is shown to be highly instrumental in the context of the control of mechanical systems with unilateral constraints. While the book presents a profound stability theory for mechanical systems with unilateral constraints, it also has a tutorial value on the modelling of such systems in the framework of measure differential inclusions. The work will be of interest to engineers, scientists, and students working in the field of non-smooth mechanics and dynamics.

Deterministic and Stochastic Time-Delay Systems El-Kebir Boukas, Zi-Kuan Liu, 2012-12-06. Most practical processes such as chemical reactor, industrial furnace, heat exchanger, etc. are nonlinear stochastic systems, which makes their control, in general, a hard problem. Currently, there is no successful design method for this class of systems in the literature. One common alternative consists of linearizing the nonlinear dynamical stochastic system in the neighborhood of an operating point and then using the techniques for linear

systems to design the controller The resulting model is in general an approximation of the real behavior of a dynamical system The inclusion of the uncertainties in the model is therefore necessary and will certainly improve the performance of the dynamical system we want to control The control of uncertain systems has attracted a lot of researchers from the control community This topic has in fact dominated the research effort of the control community during the last two decades and many contributions have been reported in the literature Some practical dynamical systems have time delay in their dynamics which makes their control a complicated task even in the deterministic case Recently the class of uncertain dynamical deterministic systems with time delay has attracted some researchers and some interesting results have been reported in both deterministic and stochastic cases But we can't claim that the control problem of this class of systems is completely solved more work must be done for this class of systems

Stability of Time-Delay Systems Keqin Gu, Vladimir L. Kharitonov, Jie Chen, 2012-12-06 This monograph is a self contained coherent presentation of the background and progress of the stability of time delay systems Focusing on techniques tools and advances in numerical methods and optimization algorithms the authors developed material which up until now has been scattered in technical journals and conference proceedings Special emphasis is placed on systems with uncertainty and stability criteria which can be computationally implemented The second edition is major update to reflect the state of art in this field greatly expanding on the original material in addition to two new chapters on Systems of Neutral Type and an Introduction to Frequency Domain Method Requiring only basic knowledge of linear systems and Lyapunov stability theory *Stability of Time Delay Systems* 2nd ed is accessible to a broad audience of researchers professional engineers and graduate students It may be used for self study or as a reference portions of the text may be used in advanced graduate courses and seminars

Automatic Control and Mechatronic Engineering III Abdel-Hamid I. Mourad, 2014-08-11 Selected peer reviewed papers from the 3rd International Conference on Automatic Control and Mechatronic Engineering ICACME 2014 June 13 14 2014 Xiamen China

Model-based Process Supervision Arun Kumar Samantaray, Belkacem Ould Bouamama, 2008-03-14 This book provides control engineers and workers in industrial and academic research establishments interested in process engineering with a means to build up a practical and functional supervisory control environment and to use sophisticated models to get the best use out of their process data Several applications to academic and small scale industrial processes are discussed and the development of a supervision platform for an industrial plant is presented

Building Software for Simulation James J. Nutaro, 2010-12-21 *Building Software for Simulation* A unique guide to the design and implementation of simulation software This book offers a concise introduction to the art of building simulation software collecting the most important concepts and algorithms in one place Written for both individuals new to the field of modeling and simulation as well as experienced practitioners this guide explains the design and implementation of simulation software used in the engineering of large systems while presenting the relevant mathematical elements concept discussions and code development The book approaches the topic from the

perspective of Zeigler's theory of modeling and simulation introducing the theory's fundamental concepts and showing how to apply them to engineering problems Readers will learn five necessary skills for building simulations of complicated systems Working with fundamental abstractions for simulating dynamic systems Developing basic simulation algorithms for continuous and discrete event models Combining continuous and discrete event simulations into a coherent whole Applying strategies for testing a simulation Understanding the theoretical foundations of the modeling constructs and simulation algorithms The central chapters of the book introduce explain and demonstrate the elements of the theory that are most important for building simulation tools They are bracketed by applications to robotics control and communications and electric power systems these comprehensive examples clearly illustrate how the concepts and algorithms are put to use Readers will explore the design of object oriented simulation programs simulation using multi core processors and the integration of simulators into larger software systems The focus on software makes this book particularly useful for computer science and computer engineering courses in simulation that focus on building simulators It is indispensable reading for undergraduate and graduate students studying modeling and simulation as well as for practicing scientists and engineers involved in the development of simulation tools *Subject Guide to Books in Print*, 2001

Viability Theory Jean-Pierre Aubin, Alexandre M. Bayen, Patrick Saint-Pierre, 2011-07-13 Viability theory designs and develops mathematical and algorithmic methods for investigating the adaptation to viability constraints of evolutions governed by complex systems under uncertainty that are found in many domains involving living beings from biological evolution to economics from environmental sciences to financial markets from control theory and robotics to cognitive sciences It involves interdisciplinary investigations spanning fields that have traditionally developed in isolation The purpose of this book is to present an initiation to applications of viability theory explaining and motivating the main concepts and illustrating them with numerous numerical examples taken from various fields *American Book Publishing Record*, 2001 *SIAM Journal on Control and Optimization* Society for Industrial and Applied Mathematics, 1977

Hybrid Feedback Control Ricardo G. Sanfelice, 2021-01-12 A comprehensive introduction to hybrid control systems and design Hybrid control systems exhibit both discrete changes or jumps and continuous changes or flow An example of a hybrid control system is the automatic control of the temperature in a room the temperature changes continuously but the control algorithm toggles the heater on or off intermittently triggering a discrete jump within the algorithm Hybrid control systems feature widely across disciplines including biology computer science and engineering and examples range from the control of cellular responses to self driving cars Although classical control theory provides powerful tools for analyzing systems that exhibit either flow or jumps it is ill equipped to handle hybrid control systems In *Hybrid Feedback Control* Ricardo Sanfelice presents a self contained introduction to hybrid control systems and develops new tools for their analysis and design Hybrid behavior can occur in one or more subsystems of a feedback system and Sanfelice offers a unified control theory framework filling an important gap in

the control theory literature In addition to the theoretical framework he includes a plethora of examples and exercises a Matlab toolbox as well as two open source versions and an insightful overview at the beginning of each chapter Relevant to dynamical systems theory applied mathematics and computer science Hybrid Feedback Control will be useful to students and researchers working on hybrid systems cyber physical systems control and automation **IEEE Transactions on Circuits and Systems** ,2006 **International Aerospace Abstracts** ,1998 Journal of Dynamic Systems, Measurement, and Control ,2007 *Forthcoming Books* Rose Army,2000 IEEE Intelligent Vehicles Symposium ,2005 *Hybrid Systems* ,1995 Vols for 1996 consist of papers presented at the 4th International Conference on Hybrid Systems

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